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Hrubes

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[54] **TRAJECTORY MEASUREMENT SYSTEM FOR UNDERWATER VEHICLES**

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[52] **U.S. Cl.** **367/131**

[58] **Field of Search** 367/131, 133, 367/907, 908, 99; 114/330, 331; 364/424.025

[56] **References Cited**

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[57] **ABSTRACT**

A system for determining the velocity and trajectory of an underwater vehicle comprises a data acquisition processor coupled to a plurality of sensors providing depth, heading, pitch and yaw data for the underwater vehicle. The acquisition processor collects data from the sensors, correlates and assembles the collected data into batches and processes the batches to determine vehicle velocity and trajectory of the vehicle relative to an earth-fixed coordinate system.

9 Claims, 4 Drawing Sheets